

Recall An element $\tau \in S_n$ is a transposition if τ is a 2-cycle: $\tau = (ij)$ for some $i, j \in \{1, \dots, n\}$.

Goal Construct a homomorphism $\text{sign}: S_n \rightarrow \{\pm 1\}$.

so that $\text{sign}(ij) = -1 \quad \forall (i, j) \in S_n$.

Aside (i) $A_n = \ker(\text{sign})$ is a normal subgroup of S_n called the alternating group.

(ii) Since sign is onto, $S_n/A_n \cong \{\pm 1\}$.

Key idea: S_n acts on the standard basis $\{e_1, \dots, e_n\}$ by permuting the vectors: for $\sigma \in S_n$, $\sigma \cdot e_i = e_{\sigma(i)}$.

This action gives rise to a collection of linear maps

$$\rho(\sigma): \mathbb{R}^n \rightarrow \mathbb{R}^n, \quad \rho(\sigma)(\sum x_i e_i) := \sum x_i e_{\sigma(i)}$$

Each $\rho(\sigma)$ is a matrix with the columns $e_{\sigma(i)}$'s:

$$\rho(\sigma) = (e_{\sigma(1)} | e_{\sigma(2)} | \dots | e_{\sigma(n)})$$

Ex $n=3, \sigma = (1 \ 2 \ 3)$

$$\rho(\sigma) = (e_{\sigma(1)} | e_{\sigma(2)} | e_{\sigma(3)}) = (e_2 | e_3 | e_1) = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

Since the columns of $\rho(\sigma)$ are basis vectors, each $\rho(\sigma)$ is an invertible matrix, that is, an element of $GL(n, \mathbb{R}) = \text{the group of } n \times n \text{ invertible matrices}$

The map $\rho: S_n \rightarrow GL(n, \mathbb{R})$ is a homomorphism:

$$\forall \sigma, \mu \in S_n \quad \forall \vec{x} = \sum x_i e_i \in \mathbb{R}^n$$

$$\rho(\sigma)(\rho(\mu)\vec{x}) = \rho(\sigma)(\sum x_i e_{\mu(i)}) = \sum x_i e_{\sigma(\mu(i))} =$$

$$= \sum_i x_i e_{(\sigma(i))} = \rho(\sigma) (\sum_i x_i e_i).$$

Note Since $\sum_{i=1}^n x_i e_{\sigma(i)} = \left(\begin{smallmatrix} & j=\sigma(i) \\ i=\sigma'(j) & \end{smallmatrix} \right) = \sum_{j=1}^n x_{\sigma^{-1}(j)} e_j$

$$\rho(\sigma) \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} x_{\sigma^{-1}(1)} \\ \vdots \\ x_{\sigma^{-1}(n)} \end{pmatrix}$$

For $\sigma \in S_n$, $\rho(\sigma)$ is called the corresponding permutation matrix.

The homomorphism $\rho: S_n \rightarrow GL(n, \mathbb{R})$ is called the permutation representation: we "represent" permutations by matrices.

Note ρ is injective since $\sigma \in \ker \rho \Leftrightarrow$

$$\rho(\sigma) = I$$

$$\Leftrightarrow (e_{\sigma(1)} | \dots | e_{\sigma(n)}) = (e_1 | e_2 | \dots | e_n)$$

$$\Leftrightarrow \sigma = id.$$

Homomorphism theorem $\Rightarrow \rho(S_n) \subseteq GL(n, \mathbb{R})$ is a subgroup isomorphic to S_n , ie each $\sigma \in S_n$ is represented by a unique matrix $\rho(\sigma)$.

Back to sign: $S_n \rightarrow GL(n, \mathbb{R})$

Consider a function $\Delta: \mathbb{R}^n \rightarrow \mathbb{R}$,

$$\Delta(x_1, \dots, x_n) = \prod_{i < j} (x_i - x_j)$$

$$\underline{Ex} \quad n=3 \quad \Delta(x_1, x_2, x_3) = (x_1 - x_2)(x_1 - x_3)(x_2 - x_3)$$

$$\underline{n=4} \quad \Delta(x_1, x_2, x_3, x_4) = (x_1 - x_2)(x_1 - x_3)(x_1 - x_4)(x_2 - x_3)(x_2 - x_4)(x_3 - x_4)$$

etc

Exercise 19.0 $\Delta(\rho(i\ i+1)(x_1 - x_n)) = -\Delta(x_1, \dots, x_n)$

$$\text{Eq} \quad \Delta(\rho(34)(x_1 - x_4)) = (x_1 - x_2)(x_1 - x_4)(x_1 - x_3)(x_2 - x_4)(x_2 - x_3)(x_4 - x_3) \\ = -\Delta(x_1, \dots, x_4).$$

In general, $\forall \sigma \in S_n$

$$\boxed{\Delta(\rho(\sigma)(x_1, \dots, x_n)) = \pm \Delta(x_1, \dots, x_n)}$$

Definition We define $\text{sign}: S_n \rightarrow \{\pm 1\}$ by
 $\text{sign}(\sigma) = \frac{\Delta(\rho(\sigma)(x_1, \dots, x_n))}{\Delta(x_1, \dots, x_n)}$

Proposition 19.1 For any $\sigma, \mu \in S_n$

$$\text{sign}(\sigma\mu) = \text{sign}(\sigma) \cdot \text{sign}(\mu),$$

i.e. $\text{sign}: S_n \rightarrow \{\pm 1\}$ is a homomorphism.

$$\begin{aligned} \underline{\text{Proof}} \quad \text{sign}(\sigma\mu) &= \frac{\Delta(\rho(\sigma\mu)\vec{x})}{\Delta(\vec{x})} = \frac{\Delta(\rho(\sigma)\rho(\mu)\vec{x})}{\Delta(\rho(\mu)\vec{x})} \cdot \frac{\Delta(\rho(\mu)\vec{x})}{\Delta(\vec{x})} \\ &= \frac{\Delta(\rho(\sigma)\vec{y})}{\Delta(\vec{x})} \cdot \frac{\Delta(\rho(\mu)\vec{x})}{\Delta(\vec{x})} = \text{sign}(\sigma) \cdot \text{sign}(\mu) \end{aligned} \quad \square$$

Note exercise 19.0 says: $\text{sign}(i\ i+1) = -1$.

Lemma 19.2 Any transposition $(i\ j)$ is a product of an odd number of transpositions of the form $(k\ k+1)$. Hence

$$\text{sign}(i\ j) = (-1)^{\text{odd power}} = -1.$$

Proof Say $i < j$ $\cdots \swarrow i \underbrace{\swarrow \cdots \swarrow}_{j-i-1 \text{ slots}} j \swarrow \cdots \swarrow$

To switch i and j we first move i past j in

$$i \leftrightarrow i+1 \leftrightarrow i+2 \leftrightarrow \cdots \leftrightarrow j \quad (j-i-1 \text{ switches})$$

Then move j back to where i was

$$i-1 \leftrightarrow i \leftrightarrow \cdots \leftrightarrow j-1 \leftrightarrow j \quad (j-i-1 \text{ switches})$$

\Rightarrow total # of switches is $2(j-i) + 1$.

\square

Aside 1) For an $n \times n$ matrix $(a_{ij})_{1 \leq i,j \leq n}$

$$(1) \det(a_{ij}) = \sum_{\sigma \in S_n} \text{sign}(\sigma) a_{1\sigma(1)} \cdots a_{n\sigma(n)}.$$

$$\begin{aligned} 2) \det(p(\sigma)) &= \det(e_{\sigma(1)} | \cdots | e_{\sigma(n)}) = \text{sign}(\sigma) \cdot 1 \cdot 1 \cdots \cdot 1 \\ &= \text{sign}(\sigma). \end{aligned}$$

If $\det: GL(n, \mathbb{R}) \rightarrow \mathbb{R}$ is constructed in a way that does not use (1) above, we could use it to construct sign :

$$\text{sign} = \det \circ p$$

where $p: S_n \rightarrow GL(n, \mathbb{R})$ is the permutation representation.

More definitions

Def (5.1.11 of Goodman) Suppose a group G acts on a set X

The stabilizer of $x \in X$ is the set

$$G_x = \text{Stab}(x) = \{g \in G \mid g \cdot x = x\}.$$

Ex $SO(3) = 3 \times 3$ orthogonal matrices w. $\det = 1$

(The group of proper rotations)

$SO(3)$ acts on \mathbb{R}^3 : $A \cdot \vec{v} := A\vec{v} \quad \forall A \in SO(3) \quad \forall \vec{v} \in \mathbb{R}^3$

$\text{Stab}(\vec{0}) = SO(3)$ since $A\vec{0} = \vec{0} \quad \forall A$.

If $\vec{v} \neq 0$, $\text{Stab}(\vec{v}) =$ rotations about the axis $\mathbb{R}\vec{v}$.

Lemma 5.1.12 The stabilizer G_x of x is a subgroup of G .

Proof (1) $\forall a, b \in G_x \quad (ab) \cdot x = a \cdot (b \cdot x) = a \cdot x = x \Rightarrow ab \in G_x$.

(2) $e \cdot x = x \Rightarrow e \in G_x$

(3) $\forall a \in G_x, \quad x = e \cdot x = (a^{-1}a) \cdot x = (a^{-1}) \cdot (a \cdot x) = a^{-1} \cdot x$
 $\Rightarrow a^{-1} \in G_x$

$\therefore G_x$ is a subgroup of G .